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***D-II Physics Hons.***

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# Maxwell's equations for static electric & magnetic field

We have ~~encountered~~ encountered the following laws, specifying the div and curl of electric & magnetic fields —

differential form

$$\textcircled{1} \quad \vec{\nabla} \cdot \vec{D} = \rho$$

$$\textcircled{2} \quad \vec{\nabla} \cdot \vec{B} = 0$$

$$\textcircled{3} \quad \vec{\nabla} \times \vec{E} = 0$$

$$\textcircled{4} \quad \vec{\nabla} \times \vec{H} = \vec{J}$$

Integral form

$$\oint \vec{D} \cdot d\vec{s} = \int \rho dV$$

→ Gauss law

$$\oint \vec{B} \cdot d\vec{s} = 0$$

(non existence of magnetic poles)

$$\oint \vec{E} \cdot d\vec{l} = 0$$

(Conservative nature of electrostatic field)

$$\oint \vec{H} \cdot d\vec{l} = \int \vec{J} \cdot d\vec{s}$$

(Ampere's law)

These eq<sup>n</sup> represent the state of e.m. theory over a century ago, when Maxwell began his work. Then Maxwell given four eqs. which are same as above eqs. —

$$\textcircled{1} \quad \vec{\nabla} \cdot \vec{D} = \rho \Rightarrow \boxed{\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}}$$

$$\textcircled{2} \quad \boxed{\vec{\nabla} \cdot \vec{B} = 0} \Rightarrow$$

$$\textcircled{3} \quad \boxed{\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}}$$

$$\textcircled{4} \quad \vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

or,  $\boxed{\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \frac{\partial \vec{D}}{\partial t}}$

above, four eqs are Maxwell's equation for Time varying field

$$\oint \vec{D} \cdot d\vec{s} = \int \rho dV$$

(Gauss's law)

$$\oint \vec{B} \cdot d\vec{s} = 0$$

$$\oint \vec{E} \cdot d\vec{l} = -\frac{\partial}{\partial t} \int \vec{B} \cdot d\vec{s}$$

(Faraday's law) —

$$\oint \vec{H} \cdot d\vec{l} = \int (\vec{J} + \frac{\partial \vec{D}}{\partial t}) \cdot d\vec{s}$$

(Ampere's law)

$$(\vec{D} = \epsilon_0 \vec{E}) \text{ —}$$

$$(\vec{B} = \mu_0 \vec{H}) \text{ —}$$



## Maxwell's Displacement Current:-

For, Ampere's law we have:

$$\boxed{\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}} \quad \text{--- (1)}$$

div of both sides

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \mu_0 (\vec{\nabla} \cdot \vec{J})$$

$$0 = \mu_0 (\vec{\nabla} \cdot \vec{J})$$

put in above eq<sup>n</sup>

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t} \quad \text{--- (A)}$$

$$0 = \mu_0 \left( -\frac{\partial \rho}{\partial t} \right)$$

or,  $\frac{\partial \rho}{\partial t} = 0$ , which is not possible,

the eq<sup>n</sup> of Continuity requires that  $\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t} \neq 0$   
This implies that Ampere's law only holds for steady current where the rate of flow of charge is const.

Let us, extend eq<sup>n</sup> (1) for time varying cond<sup>n</sup>s by adding a term to R.H.S. of eq<sup>n</sup> (1)

$$\vec{\nabla} \times \vec{B} = \mu_0 (\vec{J} + \vec{J}_D) \quad \text{--- (2)}$$

on taking, again div. of both sides

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \mu_0 (\vec{\nabla} \cdot \vec{J} + \vec{\nabla} \cdot \vec{J}_D)$$

$$0 = \mu_0 (\vec{\nabla} \cdot \vec{J} + \vec{\nabla} \cdot \vec{J}_D)$$

$$\text{or, } \vec{\nabla} \cdot \vec{J} = -\vec{\nabla} \cdot \vec{J}_D$$

$$\vec{\nabla} \cdot \vec{J}_D = \frac{\partial \rho}{\partial t} \quad \text{--- (3)}$$

from Gauss's law:-

we have

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

differentiate w.r. to time

$$\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}) = \vec{\nabla} \cdot \frac{\partial \vec{E}}{\partial t} = \frac{1}{\epsilon_0} \frac{\partial \rho}{\partial t}$$



(24)

$$\vec{\nabla} \cdot \frac{\partial \vec{E}}{\partial t} = \frac{1}{\epsilon_0} \frac{\partial \rho}{\partial t}$$

$$\text{or, } \vec{\nabla} \cdot \frac{\partial \vec{E}}{\partial t} = \frac{1}{\epsilon_0} (\vec{\nabla} \cdot \vec{J}_0)$$

$$\left\{ \because \vec{\nabla} \cdot \vec{J}_0 = \frac{\partial \rho}{\partial t} \right\}$$

$$\vec{\nabla} \cdot \left( \frac{\partial \vec{E}}{\partial t} - \frac{1}{\epsilon_0} \vec{J}_0 \right) = 0$$

$$\text{or, } \frac{\partial \vec{E}}{\partial t} = \frac{1}{\epsilon_0} \vec{J}_0$$

$$\vec{J}_0 = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\left\{ \because \vec{D} = \epsilon_0 \vec{E} \right\}$$

$$\boxed{\vec{J}_0 = \frac{\partial \vec{D}}{\partial t}}$$

put this relation in (2), then Ampere's law became

$$\boxed{\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \frac{\partial \vec{D}}{\partial t}} \quad \text{--- (4)}$$

Still the same, experimentally verified, law for steady state phenomena, but now mathematically consistent with the Continuity eq<sup>n</sup> (A). for time dependent fields. Maxwell called the added term in eq<sup>n</sup> (2)

$\vec{J}_0 = \frac{\partial \vec{D}}{\partial t}$  'displacement current'. It represents that a changing electric field causes a magnetic field.

eq<sup>n</sup> (4) can be written as,

$$\boxed{\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}}$$

$$(\vec{B} = \mu_0 \vec{H})$$

This is known as the Ampere's law for time dependent fields.